3DIGARS-PSP: A Novel Statistical Energy Function and Effective Conformational Search Strategy based \textit{ab initio} Protein Structure Prediction

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\textbf{Abstract}—To solve protein structure prediction (PSP) problems computationally, a plethora of template-based methods exist. However, there are very few \textit{ab initio} models exist. Template-based modeling relies on the existing structures and therefore is not effective for non-homologous sequence based structure prediction. Thus, \textit{ab initio} modeling is indispensable in such cases, even though it is a challenging optimization problem. To cope, we utilize an effective energy function (called 3DIGARS) and advanced search algorithm (called KGA) based \textit{ab initio} PSP, called 3DIGARS-PSP. The proposed approach deploys a memory assisted genetic algorithm to sample the energy hypersurface of the protein folding process to search the native fold of the protein. To address critical search, the proposed genetic algorithm deploys two effective operators: angle rotation and segment translation. Further, propensities of torsion angle and secondary structure distribution have been utilized to guide the conformation search. Crucial features, such as sequence-specific accessibility, hydrophobic-hydrophilic properties and torsion angles of protein residues are mined to formulate an optimized energy function, which is then combined with the advanced sampling algorithm to explore critical conformational space. Consequently, 3DIGARS-PSP performed well compared to the state-of-the-art methods for a set of low TMscore models from CASP data and \textit{E. coli} proteins.

\textbf{Index Terms}—\textit{ab initio}, conformational search, energy function, genetic algorithm, protein structure prediction

\section{Introduction}

Protein tertiary structure prediction is one of the most challenging problems in molecular and structural biology. The goal of protein tertiary structure prediction is to accurately predict the spatial position of each atom in a 3D protein from only the sequence of amino acid residues. There exist experimental approaches for protein structure prediction (PSP), e.g. X-ray crystallography and nuclear magnetic resonance (NMR) but, these methods are far too slow and expensive for PSP. Moreover, there are computational approaches available for the PSP problem. The existing computational approaches can be categorized into two broad categories \textit{i) homology modeling or template-based modeling and ii) \textit{ab initio} or \textit{de novo} modeling depending on whether similar proteins have already been experimentally solved. If proteins of the similar structure are recognized from the PDB \cite{1} library and the templates of the similar proteins are utilized to construct the target model, then this approach is called “homology modeling or template-based modeling” \cite{2}, \cite{3}, \cite{4}, \cite{5}, \cite{6}. However, if protein templates are not available, the 3D structure is built from only the sequence of amino acid residues, and this approach is called “\textit{ab initio} or \textit{de novo} modeling” \cite{7}, \cite{8}, \cite{9}, \cite{10}, \cite{11}, \cite{12}, \cite{13}, \cite{14}.

The approach of homology modeling for PSP has achieved significant success and the reason is the growing number of experimentally solved structures available in the PDB library. Nevertheless, this approach fails to produce effective structure in the absence of similar proteins. This necessitates the development of the \textit{ab initio} method for PSP. Typically, \textit{ab initio} modeling comprises of two important components \textit{i}) an accurate energy function and \textit{ii}) effective conformational search. Energy function is used to evaluate the fitness of a given conformation and in general, distinguish the native structure from native-like decoys \cite{15}, \cite{16}, \cite{17}, \cite{18}, \cite{19}. Thus, an accurate energy function which can properly distinguish the native structure from native-like decoys is a key component of the \textit{ab initio} PSP. Likewise, a search algorithm is used to explore the protein’s conformational space by generating diverse and effective conformational samples. In addition to an accurate energy function, success of the \textit{ab initio} PSP hinges on the effectiveness of conformational search method which can sample the energy hyper-surface of the protein folding process, looking for global minimum or the native fold of the protein. As a result, improvement in the accuracy of protein structure prediction can be achieved.

In this study, we develop a new algorithm, 3DIGARS-PSP for \textit{ab initio} protein structure prediction, with the focus on an elegant design of the energy function as well as the search algorithm. Our design of an energy function involves the generation of multiple 3D structural and sequence-specific energetic features using multiple data sets of known proteins and two different reference states. Subsequently, the energetic features are ranked based on the...
**Pearson Correlation Coefficient** (PCC) and their optimized combination is obtained using Genetic Algorithm (GA) [20], [21]. During optimization, the feature selection technique is used and only the features which helped improve the fitness of the GA are considered in the energy calculation of the structure. The optimized energy function is then used to evaluate the structures generated during the *ab initio* PSP process. Moreover, the design of search process involves conformational change in the structure. We achieve the conformational change in the structure by applying the GA with novel mutation and crossover operators based on angular rotation and translation capabilities.

Further, we conducted a systematic test and analysis of the proposed 3DIGARS-PSP method on the target proteins from *Critical Assessment of Protein Structure Prediction 8* (CASP8) [22] and *E. coli* proteins. We compare the models predicted by 3DIGARS-PSP with the models predicted by Rosetta [23] and I-Tasser [24] servers visually as well as in terms of the TMscore [25], [26] performance measure.

## 2 Method

### 2.1 Design of Optimal Energy Function

The energy function plays a key role in evaluating the fitness of a given conformation and guiding the conformational search process by discriminating native-like structures from an ensemble of decoy structures, generated by conformational sampling during the *ab initio* PSP process. In this work, we designed an optimized energy function whose total energy is the sum of the 6 energy features as shown in (1).

\[
E_{\text{tot}} = E_{\text{ASA} \_TDS3 \_RS1} + w_1 E_{\text{3DIGARS}} + w_2 E_{\text{ASA \_REGAd3p}_\Phi} + w_3 E_{\text{PSI \_TDS4 \_RS1}} + w_4 E_{\text{PSI \_TDS2 \_RS1}} + w_5 E_{\text{Triplet \_TDS4 \_RS1}}
\]  

(1)

where, energy features are computed from four different training datasets (TDS1, TDS2, TDS3 and TDS4) which are described under “Training Datasets for Energy Function” in Section 2.4.1 and two different reference states (RS1 and RS2) which are also described later in this section. Note that $E_{\text{3DIGARS}}$ and $E_{\text{ASA \_REGAd3p}_\Phi}$ energy features were computed from TDS1 and TDS2 respectively, in our prior work [16], [15] and are extracted from 3DIGARS3.0 [17] energy function for the purpose of this work. Furthermore, $w_1 = 1.98$, $w_2 = 0.70$, $w_3 = 1.16$, $w_4 = 0.03$, and $w_5 = 0.25$ are the weighting factors to balance the energy features, which were tuned using a GA based on a multi-objective fitness function as defined in (2).

\[
\text{Obj \_func} = (\text{Avg \_PCC} + (1.0)\text{Avg \_TMscore}) + (-1.0)\text{Avg \_Native \_Count} + \text{Avg \_Zscore})
\]  

(2)

where, Avg \_PCC is an average of the correlation coefficient for all the proteins in a dataset whereas, PCC is computed from the total energy and the structural accuracy (or TMscore) of the models in a protein, Avg \_TMscore is an average of the TMscore of the low energy models, Avg \_Native \_Count is an average number of correctly selected native structures out of decoys and Avg \_Zscore is an average of Zscores (more negative Zscores indicate that the energy function is able to clearly separate natives from decoys).

The average for all of the components of the objective function are computed by dividing the features by the count of proteins present in the optimization dataset which are described under “Optimization Datasets for Energy Function” in Section 2.4.2. The GA parameters used for energy function optimization were set to i) maximum generation of 20,000; ii) population size of 200; iii) elite rate of 5%; iv) crossover rate of 90%; and v) mutation rate of 50%. Additionally, each of the weight variables, $w_1$ through $w_5$ were represented by an 11 bit binary (1/0) encoding system.

Initially, we designed 41 energy features among which 17 of the energy features were obtained by a sequence-specific accessible surface area (ASA) energy calculation method, 20 of the energy features were obtained by a sequence-specific torsion angle (Phi and Psi) energy calculation method and 4 of the energy features were obtained from the 3DIGARS3.0 [17] energy function (1 feature for the hydrophobic-hydrophilic energy term, 1 feature for the sequence specific ASA energy term where, predicted ASA energy is computed using the REGAd3p tool [15] and 2 features for uPhi and uPsi energy terms). All other features except the features extracted from 3DIGARS3.0 energy function were generated using the outputs from DSSP [27] and Spider2 [28] programs. DSSP program provides the real value assignment of the phi-psi angle pair and ASA from the structure of the protein. Whereas, Spider2 is a program which provides predicted phi-psi angle pair and ASA from the sequence of amino acids (fasta sequence). Among 41 features, only 6 of the features were finally considered for total energy calculation and the rest of the features were ruled out using the feature selection technique as described in Algorithm 1.

### 2.1.1 Sequence-specific ASA Energy Features

The sequence-specific ASA energy feature, $E_{\text{ASA}}$ is computed from the probability $P(\Delta ASA \_i \mid AA_i)$ of the prediction error of ASA ($\Delta ASA = ASA_{\text{Real}} - ASA_{\text{Pred}}$) for a given amino acid type, AA, over all the ASA along the sequence. The sequence-specific ASA energy feature is mathematically represented as:

\[
E_{\text{ASA}} = -RT \sum_i P(\Delta ASA \_i \mid AA_i)
\]  

(3)

where, $R$ is the gas constant and $T$ is the temperature. The ASA_{Real} and ASA_{Pred} terms in the prediction error calculation are obtained from DSSP [27] and Spider2 [28] for a given amino acid type, AA. Two different probability functions $P(\Delta ASA \_i \mid AA_i)$ and $P(\Delta ASA \_i \mid AA, SS)$ were obtained from four different training datasets (TDS1, TDS2, TDS3 and TDS4, discussed under “Dataset Collection” in Section 2.4) and two different reference states. Reference state indicates the distribution of atoms in a protein system.
Algorithm 1: Energy Feature Selection Based on Optimization Dataset

1. For each model in a protein set
   - Compute (41) energy features and TMscore values.
2. For each protein set
   - Compute PCC between each energy feature and TMscore.
3. For each dataset
   - Compute average of the PCC for individual energy features.
4. Compute average of PCC over all the dataset for individual energy features.
5. Compute the absolute value of the average PCC for individual energy features.
6. Rank the features in descending order of absolute average PCC.
7. Start the energy function optimization with the top most feature (one with highest absolute average PCC) and incrementally add the feature to total energy with weighting factor if the addition of the feature helps improve the objective function. Inversely, if the feature does not improve the objective function then the feature is discarded and next feature in the list is tested.

Algorithm 2: Phi Angle Rotation

1. Select an axis passing through two points p1 and p2 (atoms Nα and Cα).
2. Translate point p1 (atom Nα) to the origin.
3. Rotate point p2 (atom Cα) onto the Z-axis.
4. Rotate the segment of the structure after point p2 around the Z-axis.
5. Translate the axis passing through two points p1 and p2 to the original orientation.
6. Translate the structure to the original position.

when the interaction is turned off. To test the influence of different reference states, we employed two different reference states: i) based on conditional probability proposed by Samudrala and Moult [29] and ii) based on averaging technique proposed by Hoque et al. [30]. We generated 16 sequence-specific ASA based features by using Spider2 ASA predictor, two different probability functions, four different training datasets and two different reference states.

2.1.2 Sequence-specific Torsion Angle Energy Features

The sequence-specific torsion angle energy feature, $E_\theta$ is computed from the probability $P(\Delta \theta | AA_i, SS_i)$ of the prediction angle error ($\Delta \theta = \theta^{\text{Real}} - \theta^{\text{Pred}}$) for a given amino acid type, AA, and predicted secondary structure, SS, over all the torsion angles along the sequence. The sequence-specific torsion angle energy feature is mathematically represented as in (4).

$$E_\theta = -RT \sum_i \ln P(\Delta \theta_i | AA_i, SS_i)$$  \hspace{1cm} (4)

where, $R$ is the gas constant and $T$ is the temperature. The $\theta^{\text{Real}}$ and $\theta^{\text{Pred}}$ terms in the prediction angle error calculation are obtained from DSSP and Spider2 programs for a given amino acid type, AA, and predicted secondary structure, SS. The probability function $P(\Delta \theta | AA_i, SS_i)$ was obtained from four different training datasets and two different reference states similar to the ASA energy feature extraction as stated above. We generated 16 sequence-specific torsion angle (phi and psi) based features by using four different training datasets and two different reference states. Two additional features based on uPhi and uPsi were reproduced using reference states based on the averaging technique proposed by Hoque et al. [30] whereas, these features were originally generated using a conditional probability based reference state in 3DIGARS3.0 [17].

2.1.3 Sequence-specific ASA and Torsion Angle Energy Feature Computed from Amino Acid Triplets

The sequence-specific ASA energy feature from amino acid triplets, $E_{ASA, Triplet}$ is computed from the probability $P(ASA_i | AA_{i-1}, AA_i, SS_i)$ of the error of ASA ($ASA_i = ASA^{\text{Real}} - ASA^{\text{Pred}}$) for a given amino acid type, AA, over all the ASA computed along the sequence. Similarly, the sequence-specific torsion angle energy feature for amino acid triplets, $E_{\theta, Triplet}$ are computed from the probability $P(\Delta \theta_i | AA_{i-1}, AA_i, SS_i)$ of the prediction angle error ($\Delta \theta = \theta^{\text{Real}} - \theta^{\text{Pred}}$) for a given amino acid type, AA, and predicted secondary structure, SS, over all the torsion angles computed along the sequence. The sequence-specific ASA energy feature for an amino acid triplet is mathematically represented as in (5).

$$E_\theta = -RT \sum_i \ln P(\Delta \theta_i | AA_{i-1}, AA_i, SS_i)$$  \hspace{1cm} (5)

where, $\Delta \theta_i$ represents an amino acid triplet at position ‘i’ in the sequence. Similarly, the sequence-specific torsion angle energy feature for amino acid triplets is mathematically represented as in (6):

$$E_\theta = -RT \sum_i \ln P(\Delta \theta_i | AA_{i-1}, AA_i, SS_i)$$  \hspace{1cm} (6)

where, $\Delta \theta_i$ again represents an amino acid triplet at position ‘i’ in the sequence. By this approach, we generated 1 feature for sequence-specific ASA energy and 2 features for sequence-specific torsion (1 for phi and 1 for psi) energies.

2.2 Design of Conformational Search

Effective conformational search is another critical component of ab initio protein structure prediction, where the design of conformational change operators which can effectively sample the energy hyper-surface of the protein folding process, looking for the global minimum or the native fold of the protein is essential for improving the efficiency of search algorithms. Towards this goal, we designed a memory assisted GA which involves two types of conformational change operators i) angle rotation; and ii) segment translation. Our mutation operation involves phi or psi angle rotation and crossover operation involves segment translation followed by phi or psi angle rotation at the crossover point. Rotation of phi and psi angles involves rotation about an arbitrary axis. We consider this arbitrary axis to pass through the atoms that are involved in phi and
psi angle formation. Torsion angle phi involves the backbone atoms C(O)$_{n-1}$-N$_{i}$-C($\alpha$)$_{i}$-C(O)$_{n}$ and psi involves the backbone atoms N$_{i}$-C($\alpha$)$_{i}$-C(O)$_{n}$-N$_{n+1}$. To perform phi angle rotation we follow steps described in Algorithm 2. In a like manner, psi angles are rotated by the similar steps described in Algorithm 2. However, the points p1 and p2 here instead represent atoms C($\alpha$)$_{i}$ and C(O)$_{n}$ respectively. Moreover, to generate child structures of GA by crossing over parent structures, the segment translation technique is employed. A set of possible crossover points are selected based on the secondary structure information. All amino acid indexes except the amino acids belonging to the beta sheet secondary structure type (either E or B) are considered as possible crossover points. This is because we want to preserve beta sheet regions in the structure from random changes during the crossover operation and perform more careful changes in the beta sheet region while performing mutation operation.

During the crossover process we generate four child structures from two parent structures and a structure with best fitness saved in the memory [20]. After selecting a crossover point, first child structure is created by copying atoms starting at position one to the crossover point from first parent and the translated atoms starting at crossover point plus one to the last atom from the second parent. Similarly, second child structure is created by copying atoms starting at position one to the crossover point from first parent and the translated atoms starting at crossover point plus one to the last atom from the structure in memory. Alternatively, the third child structure is created by copying the translated atoms starting at position one to one less than the crossover point from second parent and the atoms starting at the crossover point to the last atom from first parent. Similarly, the fourth child structure is created by copying the translated atoms starting at position one to one less than the crossover point from the structure in memory and the atoms starting at the crossover point to the last atom from first parent. The process of creating child chromosomes from parents is shown in Supplementary Fig. S1. After segment translation complete the torsion angles of the child structure at the crossover point are rotated back to the original torsion angles of parent structures. This is done to ensure that the secondary structure type before crossover and after crossover remains consistent. Furthermore, we update the fragments of the structure in the memory with the fragments that results in better fitness during the crossover process. This ensures that the segment that yields better fitness is preserved and used in the next round of crossover operation during the search process. The memory assisted GA presented in this work is an extension of KGA implemented specifically for the purpose of ab initio PSP. For the basics on KGA please refer [20] and for the detailed implementation of memory assisted GA please refer to the 3DIGARS-PSP Software code available freely online at: http://cs.uno.edu/~tamjid/Software/ab_initio/v2/PSP.zip.

2.3 Ab initio Protein Structure Prediction Method (3DIGARS-PSP)

Protein structure in 3DIGARS-PSP are represented by backbone atoms N, Ca, C and O. We start by initializing some of the chromosomes of the GA population with the Cartesian coordinates of the backbone atoms of the models obtained from I-Tasser [24] and Rosetta [23] servers. The rest of the chromosomes are initialized by single point torsion angle changes (rotation). To change the phi or psi angles effectively, we collected the frequency of occurrence of 20 different amino acids with different phi-psi torsion angle pairs. Both phi and psi angles are divided into 120 bins with an interval of 3 degree, summarized from the 4,332 high-resolution experimental structures. An example that shows how the frequency of occurrence is computed is as follows: if amino acid “ALA” has phi angle of -178 degrees and psi angle of 179 degrees, the frequency count for amino acid “ALA” at psi index zero and phi index zero will be increased by one. The frequency distribution obtained for each amino acid is further categorized into zones by looking at the cluster of the frequency values. To update the phi or psi angle of a certain amino acid type (aa_type) first, the torsion angle type (tor_type) is selected randomly. Next, the zone index (zone_ind) belonging to aa_type is selected randomly. Then, the roulette wheel selection method is applied to select the most probable torsion angles (namely, pPhi or pPsi) belonging to the zone_ind. Later, if tor_type = phi angle, we select a random phi (say, rPhi) between pPhi-3 and pPhi and rotate the current phi angle to achieve rPhi angle. Whereas, if tor_type = psi angle, we select a random psi (rPsi) between pPsi and pPsi+3 and rotate current psi angle to achieve rPsi angle.

The change of the torsion angles are also guided by the secondary structure (SS) types of the amino acids which are mined from the 4,332 high-resolution experimental structures. To mine the SS types, first, we run the DSSP [27] program on the experimental structures to obtain the phi-psi angle pair and the SS type for each of the amino acids in each of the proteins. DSSP output gives eight different SS types (E, B, H, G, I, T, S and U) which are broadly categorized into four different SS types (H, E, T and U). The SS types “E and B” are considered as “E”, “H, G and I” are considered as “H”, “T and S” are considered as “T” and a blank is considered as “U or undefined”. Using phi-psi angle pair and SS types, we obtain the index in our SS frequency table and increase the frequency count of the cell in the frequency table by one. E.g. if amino acid “ALA” has a phi angle of -178 degrees, a psi angle of 179 degrees, and the SS type as “H” the frequency count for amino acid “ALA” at psi index zero, phi index zero and SS index zero is increased by one. Similarly, if amino acid “ALA” has a phi angle of -178 degrees, a psi angle of 179 degrees and the SS type as “E” the frequency count for amino acid “ALA” at psi index zero, phi index zero and SS index one is increased by one. Later, the SS type which has the largest frequency count is assigned to the given amino acid having a certain phi-psi angle. Additionally, we collect the phi-psi angle pairs belonging to the H and E secondary structure types and group them into helix and beta groups. We utilize the phi-psi angle pairs belonging to the helix or sheet group to update the phi or psi angles that results in the clash within the structure.

Moreover, the random change of phi or psi angles
within the structure could produce low-resolution structures. In other words, random changes could destroy the

Algorithm 3: Change in Phi or Psi Angles Constrained by Beta Condition

1. Check if AAi belongs to SS type “E”.
2. Check if AAi satisfies Beta Condition
   - If TRUE
     - Accept the change in Phi or Psi angle if new Phi-Psi angle pair belongs to SS type “E”.
     - If new Phi-Psi angle pair belongs to SS type other than “E”.
     - Update the angle under consideration (Phi or Psi) with the most probable torsion angles from the beta group based on the roulette wheel selection mechanism.
   - If FALSE
     - If new Phi-Psi angle pair belongs to SS type “H”
     - Update the angle under consideration (Phi or Psi) with the most probable torsion angles from the helix group based on the roulette wheel selection mechanism.
     - If new Phi-Psi angle pair belongs to SS type other than “H”
     - The rotation of Phi or Psi angle is performed to achieve the new Phi-Psi angle pairs.

A conserved beta sheet regions of the structure. To overcome this issue, we apply a beta smoothing technique. An amino acid (AAi) is considered to satisfy the beta condition if any of the following conditions are satisfied: i) AAi−1 and AAi+1 both has SS type “E”; ii) AAi−1 and AAi+2 both has SS type “E”; and iii) AAi+1 and AAi+2 both has SS type “E”. AAi is the amino acid that is selected for change. To change the phi or psi angle of the AAi, we follow the steps shown in Algorithm 3. Furthermore, changes in phi or psi angles could result in a clash between atoms within the structure. To prevent clashes, we check the distance between all possible Cα atom pairs within the structure and discard the change if Cα-Cα distance is less than 3.6 Å. If the change in phi or psi angles of the current residue results in a clash then a new residue position is selected for the change.

In our implementation, before applying the energy function to evaluate the fitness of the structure, we obtain the full atomic model from the backbone model using Oscar-star [31]. The flowchart of 3DIGARS-PSP method is shown in Fig. 1.

For effective conformational search, the parameters of the GA were configured as: i) maximum generation of 300; ii) population size of 100; iii) elite rate of 5%; iv) crossover rate of 70%; and v) mutation rate of 60%.

We started building the ab initio PSP in the same year that we participated in the 2016 CASPI12 competition as team “Spiders” with our PSP program that was not fully developed and thus could not provide an impressive outcome. However, we have completed the program with the finest ingredients such as a high performing energy function [15], [16], [17], [30] and an effective sampling algorithm [20] and fixed the known bugs – our current ab initio PSP program namely, 3DIGARS-PSP, became very competitive with 5.56% better than Rosetta and 1.51% better than I-Tasser based on the benchmark dataset TAI16 (see Section 2.4.3 for TAI16 dataset and Section 3.2 for the detailed results). The free code with dataset is available at: http://cs.uno.edu/~tamjid/Software/ab_initio/v2/PSP.zip.

2.4 Data Collection

This section discusses the training, optimization and test dataset collected for training and optimization of our energy function and testing of our ab initio method.

2.4.1 Training Datasets for Energy Function

We collected three different sets of training data and created the fourth training set by combining the three, to train our energy function and obtain multiple features.

2.4.1.1 Training Datasets1 (TDS1)

The experimental structures (proteins) in this set were obtained from the PDB server. The proteins with unknown residues as well as with missing residues anywhere except for five terminal residues on either side were rejected to avoid any noise in the data. The final dataset consists of 4,332 proteins with resolution \( \leq 2.5\) Å, single chain proteins, and a sequence identity cutoff of 100%. This dataset was published previously and used as training data for the 3DIGARS [16] energy function. In this work, we discarded 8 of the proteins which consisted of only alpha carbon atoms as the DSSP [27] program requires the full atomic structure to compute phi and psi angles and the SS type for each amino acid. The resulting dataset consists of 4,324 proteins, which were used to generate the energy function features in this work.
2.4.1.2 Training Datasets2 (TDS2)
TDS2 was prepared from the PDB and consists of 1299 proteins after data purification. Initially, 2,793 proteins (both single and multiple chains) were collected from the PDB with the following data collection parameters: i) solved by X-ray crystallography; ii) resolution ≤ 1.5Å; iii) residue length ≥ 40; and iv) 30% sequence identity cutoff. Then, the proteins were refined to keep only those with a 25% sequence identity cutoff. Next, the proteins with unknown residues and missing Cartesian coordinates were discarded to avoid any noise in the data. This dataset is the same as the dataset used to generate the sequence-specific ASA based energy feature in the 3DIGARS2.0 [15] energy function.

2.4.1.3 Training Datasets3 (TDS3)
TDS3 consists of 2,479 high-resolution (resolution lower than 3Å), non-redundant (sequence identity < 25%) proteins taken from the protein sequence culling server, PISCES [32]. The proteins in this set have 500 or fewer amino acid residues. This dataset is the same as the dataset implemented in training and testing of the SPINE X [33] server.

2.4.1.4 Training Datasets4 (TDS4)
TDS4 is a combination of TDS1, TDS2 and TDS3.

2.4.2 Optimization Datasets for Energy Function
To optimize the weights of the energy function, we collected the structures submitted in four Critical Assessment of Protein Structure Prediction’s (CASP); CASP8 [22], CASP9 [34], CASP10 [35] and CASP11 [36]. Furthermore, the native structures for the proteins were obtained from Zhang Lab [37], [38], [39], [40]. The native structures were only used for TMscore based structure assessment of our ab initio method. We carried out the following two-step refinement to ensure quality optimization set collection: i) proteins that have missing residues were removed from the optimization set; ii) if the models contain an additional number of residues at the beginning and end of the structure compared to the native structure, the additional residues at the beginning and end were chopped off from the models. After filtration, the CASP8 set consists of 73 proteins, CASP9 set consists of 82 proteins, CASP10 set consists of 67 proteins and CASP11 set consists of 59 proteins. Furthermore, CASP8, CASP9 and CASP10 consists of 300 models per protein and CASP11 consists of 200 models per protein on average.

2.4.3 Test Datasets for Ab Initio PSP (TAI16)
To assess the robustness of the 3DIGARS-PSP method, we collected the models with TMscore < 0.5 submitted by the Rosetta and I-Tasser servers in the CASP8 challenge. We found that, among 73 proteins, 16 of the proteins have TMscores < 0.5 for the models submitted by Rosetta and I-Tasser. We name this benchmark set of 16 proteins as TAI16. We compared our method with the Rosetta and I-Tasser methods based on these 16 proteins as we believe that they represent the true ab initio predictions by these methods. Additionally, we randomly collected three challenging proteins from the E. coli genome to test the effectiveness of our method. Two of the proteins (PDB id:}

\begin{table}[h]
\centering
\begin{tabular}{|c|c|c|c|}
\hline
Dataset & Objective Function Components & \multicolumn{3}{c|}{Average TMscore} \\
\hline & & Native & Count & Zscore \\
\hline
CASP8 (73) & -0.7003 & 0.6628 & 23 & -0.9736 \\
CASP9 (82) & -0.7049 & 0.6305 & 15 & -0.8083 \\
CASP10 (67) & -0.6654 & 0.6614 & 24 & -1.3768 \\
CASP11 (59) & -0.6450 & 0.5626 & 17 & -1.1600 \\
Average & -0.6789 & 0.6293 & 19.75 & -1.0797 \\
\hline
\end{tabular}
\caption{Values of Objective Function Component while using the highest ranked feature.}
\end{table}

\begin{table}[h]
\centering
\begin{tabular}{|c|c|c|c|c|}
\hline
Dataset & Objective Function Components & \multicolumn{3}{c|}{Average TMscore} \\
\hline & & Native & Count & Zscore \\
\hline
CASP8 (73) & -0.70189 & 0.6735 & 44 & -1.6242 \\
CASP9 (82) & -0.6888 & 0.6482 & 46 & -1.4988 \\
CASP10 (67) & -0.6008 & 0.6739 & 43 & -2.0135 \\
CASP11 (59) & -0.6606 & 0.5740 & 34 & -1.7927 \\
Average & -0.6537 & 0.6424 & 41.75 & -1.7323 \\
\hline
\end{tabular}
\caption{Values of Objective Function Component while using six of the final energy features.}
\end{table}

* Total number of proteins available in corresponding dataset.

1k4nA and zp7vA) have residue length > 150 and the other protein (PDB id: 2z9hA) has residue length < 150.

3 Results
Here we discuss the robustness of our approach based on obtained results and analysis.

3.1 Results of the Energy Function Optimization
After ranking the features based on average PCC between the total energy and the model’s structural accuracy (TMscore), we sequentially added and ruled out the features based on their importance in improving the objective fitness during energy function optimization. In Table 1 and Table 2, we show the improvements we achieved in our energy function based on the components of the objective function: i) Average PCC; ii) Average TMscore; iii) Native Count; and iv) Average Zscore. The “Average PCC” column of Table 1 and Table 2 shows that there is a slight decrement in the average PCC. Nonetheless, from “Native Counts” column of Table 1 and Table 2, we can clearly see that the optimized energy function with 6 energy features results in 111.39% improvement and is able to select more natives from the dataset of decoy structures (CASP8, CASP9, CASP10 and CASP11), which is the primary objective of the energy function. Furthermore, from the “Average TMscore” column of Table 1 and Table 2, it is evident that the improved energy function is able to select the best models from an ensemble of decoys based on the average
TMscore with a percentage improvement of 2.08%. Similarly, based on the “Average Zscore”, the optimized energy function is improved by 60.44%. This shows the significance of our multi-objective optimization technique in improving the accuracy of the energy function.

3.2 Results of the 3DIGARS-PSP Method

We evaluated the performance of the 3DIGARS-PSP method on the benchmark set TAI16, which consist of 16 proteins. Each of the proteins in TAI16 consist of low TMscore models (TMscore < 0.5) submitted by the I-Tasser and Rosetta servers in CASP8. The models submitted by Rosetta and I-Tasser were separately used as initial seeds in our program. In Table 3, we compare the performance of the 3DIGARS-PSP method with Rosetta based on the TMscore (structure assessment criteria). Based on the average TMscore of the first model out of the five, in set TAI16 submitted by Rosetta, the average TMscore of the 3DIGARS-PSP models is 3.11% better than Rosetta (see Table 3, column “Rosetta (First Model)”). Moreover, based on the average of the average TMscore of 5 models, in set TAI16 submitted by Rosetta, 3DIGARS-PSP achieves a 5.56% improvement over Rosetta (see Table 3, column “Rosetta (Average of 5 Models)”).

In Table 4, we compare the performance of 3DIGARS-PSP method with I-Tasser based on the TMscore. Depending on the average TMscore of the first model out of the five, in set TAI16 submitted by I-Tasser, the average TMscore of the 3DIGARS-PSP method is 0.21% better than I-Tasser (see Table 4, column “I-Tasser (First Model)”). Similarly, based on the average of the average TMscore of 5 models in set TAI16 submitted by I-Tasser, 3DIGARS-PSP results in 1.51% improvement over I-Tasser (see Table 4, column “I-Tasser (Average of 5 Models)”). From Table 3 and 4 it is evident that 3DIGARS-PSP provides superior performance over Rosetta and comparably better performance over I-Tasser. Also, it is important to note that both Rosetta and I-Tasser are template based methods.

In addition to comparisons based on TMscore, it is important to compare the 3D structure of the predicted model with the native structures, because it is the structure of the protein which is responsible for its functionality. Following this, in Fig. 2 and 3, we visually compare the alignment of the model predicted by 3DIGARS-PSP on native (top) and the first of the 5 models predicted by Rosetta and I-Tasser on native (bottom) for two *E. coli* proteins (PDB ID: 2p7vA and PDB ID: 1k4nA), respectively. In addition, we provide the visual illustration and comparison of models predicted by 3DIGARS-PSP, Rosetta and I-Tasser by aligning the predicted models on their respective native crystal structures for three challenging proteins from the *E. coli* genome (see Supplementary Materials, which can be found on the Computer Society Digital Library). Supplementary Fig. S2 through S5, shows the alignment of the model predicted by 3DIGARS-PSP on native (top) and the first of the 5 models predicted by either Rosetta or I-Tasser on native (bottom). Even though the TMscores of the models predicted by 3DIGARS-PSP are slightly less (different after second or third decimal places) than the TMscore of the first out of 5 models by Rosetta and I-Tasser, the 3D structures are of similar resolution and quality. Supplementary

<table>
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<tr>
<th>Protein ID</th>
<th>3DIGARS-PSP</th>
<th>Rosetta (Average of 5 Models)</th>
<th>Rosetta (First Model)</th>
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<tr>
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<td>0.298941 (5.56%)&lt;sup&gt;a&lt;/sup&gt;</td>
<td>0.306719 (3.11%)&lt;sup&gt;a&lt;/sup&gt;</td>
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<sup>a</sup> Percentage of improvement of 3DIGARS-PSP over Rosetta based on average TMscore of 5 models and average of TMscore of the first models respectively.

<table>
<thead>
<tr>
<th>Protein ID</th>
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<th>I-Tasser (Average of 5 Models)</th>
<th>I-Tasser (First Model)</th>
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<td>T0504</td>
<td>0.2483</td>
<td>0.26766</td>
<td>0.2578</td>
</tr>
<tr>
<td>Average</td>
<td>0.333875</td>
<td>0.328836 (1.51%)&lt;sup&gt;a&lt;/sup&gt;</td>
<td>0.333175 (0.21%)&lt;sup&gt;a&lt;/sup&gt;</td>
</tr>
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</table>

<sup>a</sup> Percentage of improvement of 3DIGARS-PSP over I-Tasser based on average TMscore of 5 models and average of TMscore of the first models respectively.
Fig. 2. E. coli protein (PDB ID: 2p7vA); top – superposition of 3DI-
GARS-PSP model on native (TMscore = 0.9341); bottom – superpo-
sition of top Rosetta model (First Model) on native (TMscore = 0.944).
Natives are shown in cyan and pink and predicted models are shown
in red and yellow.

Fig. S2, illustrates an example of protein: 1k4nA from the
E. coli genome; function of this protein is unknown. Similarly,
supplementary Fig. S3 and S5, illustrates an example
of protein: 2z9hA from the E. coli genome; involved in for-
motion of a specific microcompartment in the cell in which
the metabolism of potentially toxic by-products takes
place. Finally, Supplementary Fig. S4, illustrates an exam-
ple of protein: 2p7vA from the E. coli genome; it performs
a function of binding to a sigma factor and stopping, pre-
venting or reducing the rate of its transcriptional activity.

4 CONCLUSIONS

We have proposed a new and advanced algorithm, 3DI-
GARS-PSP, for \textit{ab initio} protein structure prediction. In
3DIGARS-PSP, the backbone atoms (N, Ca, C and O) in a
Cartesian coordinate system define protein conformations. Representing protein conformation by only backbone at-
oms is our first step to reduce the large search space. In a
subsequent step, we reduce the search space by deploying
a memory assisted GA which involves two types of confor-
mational change operators \textit{i}) angle rotation; and \textit{ii}) seg-
ment translation. Moreover, we perform torsion angle and
secondary structure distribution guided changes instead of
random sampling to generate lower energy conformations.

We show that our optimized energy function consisting
of 6 energy features, computed from sequence-specific ac-
cessibility, hydrophobic-hydrphilic properties and tor-
sion angles is able to select a higher number of native struc-
tures from the CASP decoy sets. Also, when tested on the
CASP decoy set, our energy function is found to select the
low energy conformation decoys more accurately based on
TMscore and Z-scores.

Combining improved sampling and an optimized energy
function attains improvement over Rosetta and I-Tasser
template based methods, based on the test performed on
the low TMscore models, selected from CASP8 dataset
(TAI16). Our method showed 5.56\% and 3.11\% improve-
ment over Rosetta based on the average of the average
TMscores of the top 5 models and average of the first mod-
els, on the benchmark set TAI16, respectively. Similarly,
when compared with I-Tasser, our method showed 1.51\% and
0.21\% improvement based on average of the average
TMscores of the top 5 models and average of the first mod-
els, on the benchmark set TAI16, respectively. Furthe-
more, sufficiently accurate alignment of models predicted
by 3DIGARS-PSP on the known structures for three \textit{E. coli}
proteins also shows that our method is comparable with
two of the top performing state-of-the-art approaches. De-
spite notable improvement in this work, continuous efforts
in both aspects of energy function development and con-
formational search improvement are still necessary to im-
prove the accuracy of the \textit{ab initio} protein structure predic-
tion.

ACKNOWLEDGMENT

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Supplementary Information

for

3DIGARS-PSP: A Novel Statistical Energy Function and Effective Conformational Search Strategy based \textit{ab initio} Protein Structure Prediction

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<table>
<thead>
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<th>Supplementary Item</th>
<th>Title</th>
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<tbody>
<tr>
<td>Supplementary Figure 1</td>
<td>Process of generating child chromosomes from parents in memory assisted genetic algorithm. The superscript “T” e.g. for “X₄₆Tₙ” represents the translated value of “X₄₆ⁿ”.</td>
</tr>
<tr>
<td>Supplementary Figure 2</td>
<td>E. coli protein (PDB ID: 1k4nA); top – superposition of 3DIGARS-PSP model on native (TMscore = 0.9723); bottom – superposition of top Rosetta model (First Model) on native (TMscore = 0.996). Natives are shown in cyan and pink and predicted models are shown in red and yellow.</td>
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<tr>
<td>Supplementary Figure 3</td>
<td>E. coli protein (PDB ID: 2z9hA); top – superposition of 3DIGARS-PSP model on native (TMscore = 0.9558); bottom – superposition of top Rosetta model (First Model) on native (TMscore = 0.9859). Natives are shown in cyan and pink and predicted models are shown in red and yellow.</td>
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<tr>
<td>Supplementary Figure 4</td>
<td>E. coli protein (PDB ID: 2p7vA); top – superposition of 3DIGARS-PSP model on native (TMscore = 0.8133); bottom – superposition of top I-Tasser model (First Model) on native (TMscore = 0.874). Natives are shown in cyan and pink and predicted models are shown in red and yellow.</td>
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<td>Supplementary Figure 5</td>
<td>E. coli protein (PDB ID: 2z9hA); top – superposition of 3DIGARS-PSP model on native (TMscore = 0.9631); bottom – superposition of top I-Tasser model (First Model) on native (TMscore = 0.9754). Natives are shown in cyan and pink and predicted models are shown in red and yellow.</td>
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</tbody>
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